

# **Recent Advances in Random Vibrations of Nonlinear Systems for Reliability, Durability and Accelerated Testing**

**Zissimos P. Mourelatos, Ph.D.**

Professor, John F. Dodge Chair of Engineering

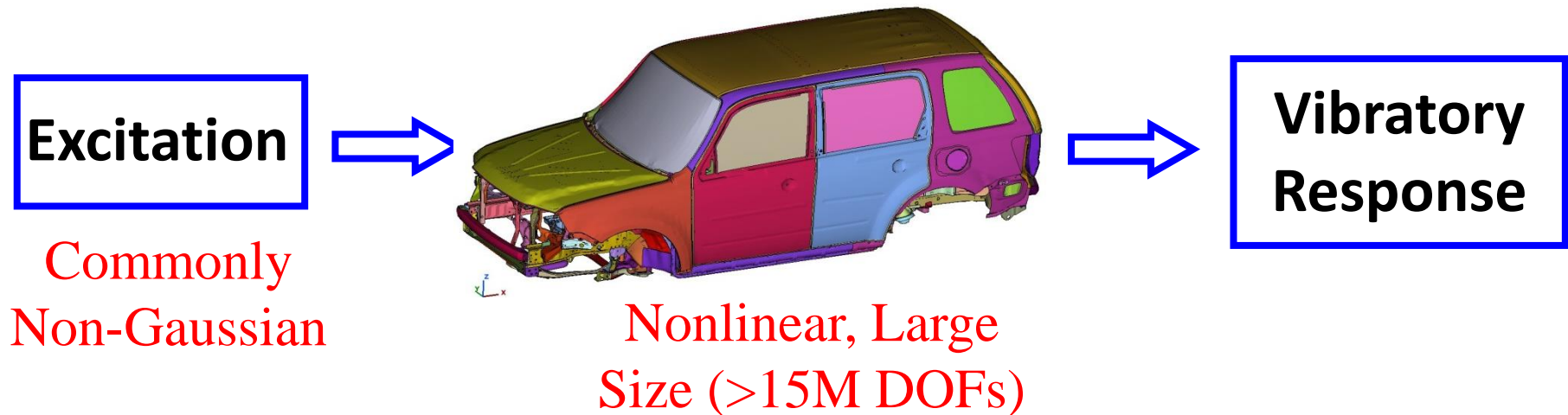
Mechanical Engineering Department  
Oakland University

August 30, 2018

# Overview

- Motivation: Reliability, Durability, ALT
- Background Theory
  - Characterization of input and output process (linear and nonlinear vibratory systems)
  - Fatigue Reliability/Durability
- Fatigue Life Estimation of Nonlinear Vibratory Systems under Gaussian or Non-Gaussian Loading
- Accelerated Life Testing (ALT)
  - Enhanced ALT design using Saddlepoint Approximation (SPA)
- Summary and Conclusions

# Motivation (Reliability, Durability, ALT)

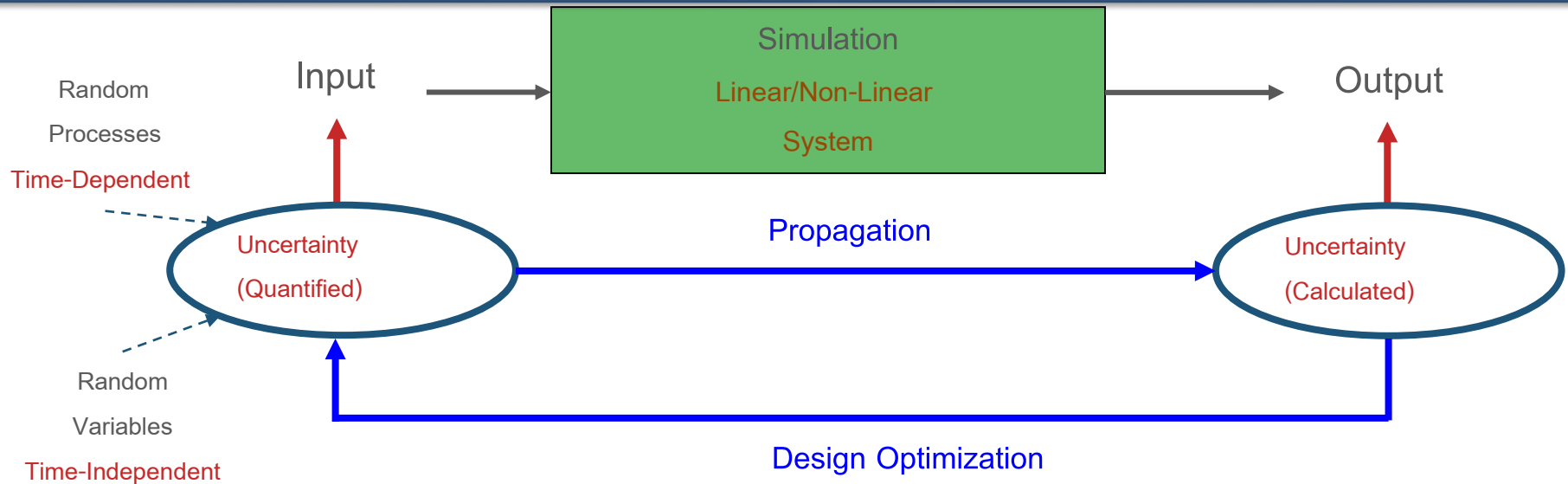


Vibration Analysis is Computationally Intensive

Deterministic Design Optimization Requires MANY Vibration Analyses

Probabilistic Design Optimization Requires EVEN MORE Vibration Analyses

# Design Under Uncertainty



## Challenges:

- Quantification of **input** random processes (Gaussian / Non-Gaussian)
- Propagation of Uncertainty to characterize **output** random processes

(Linear/Nonlinear System – Gaussian / Non-Gaussian processes)

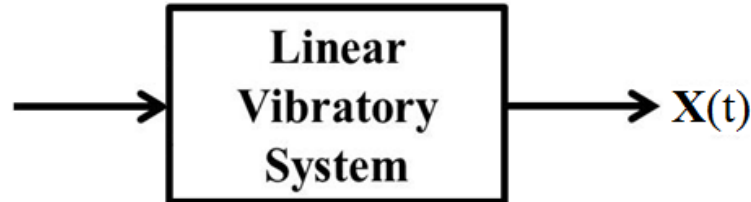
- How to reduce the **number of system simulations**?
- How to reduce computational **cost of each simulation** for very large vibratory systems (millions of DOFs) ?

# Input-Output Relationships for Vibratory Systems

**Case 1:**

Gaussian

$F(t)$

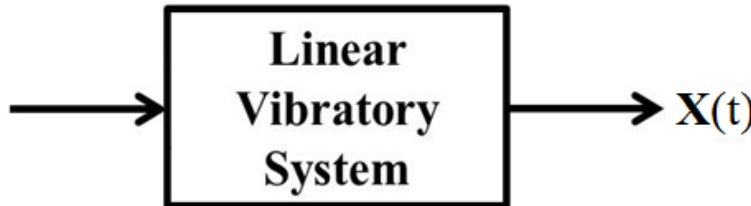


Gaussian

**Case 2:**

Non-Gaussian

$F(t)$

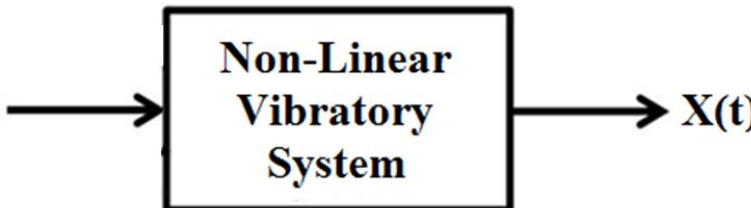


Non-Gaussian

**Case 3:**

Gaussian

$F(t)$

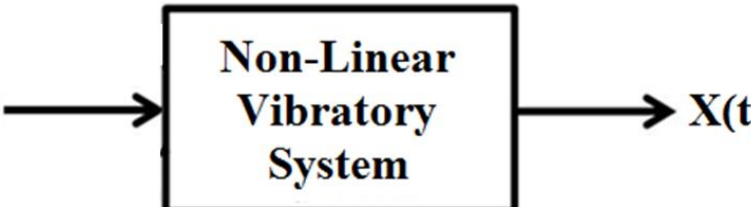


Non-Gaussian

**Case 4:**

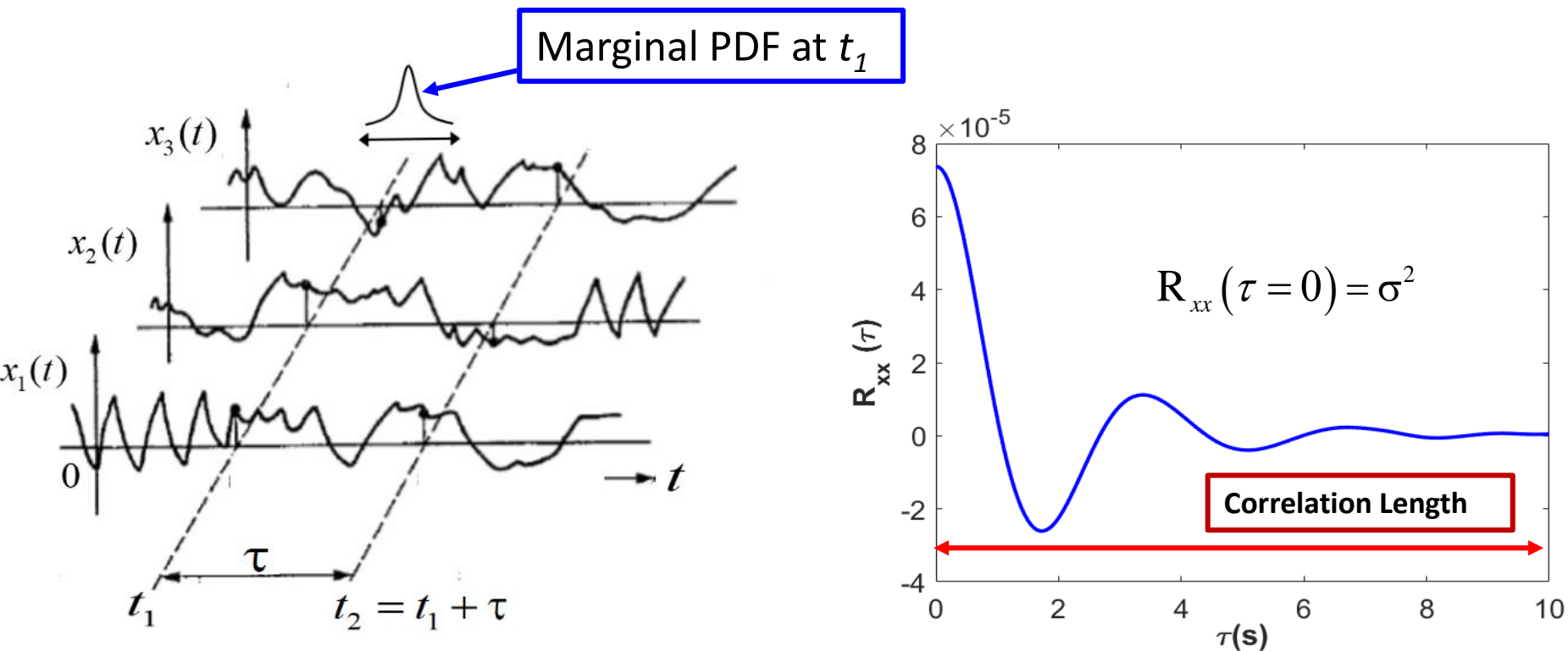
Non-Gaussian

$F(t)$



Non-Gaussian

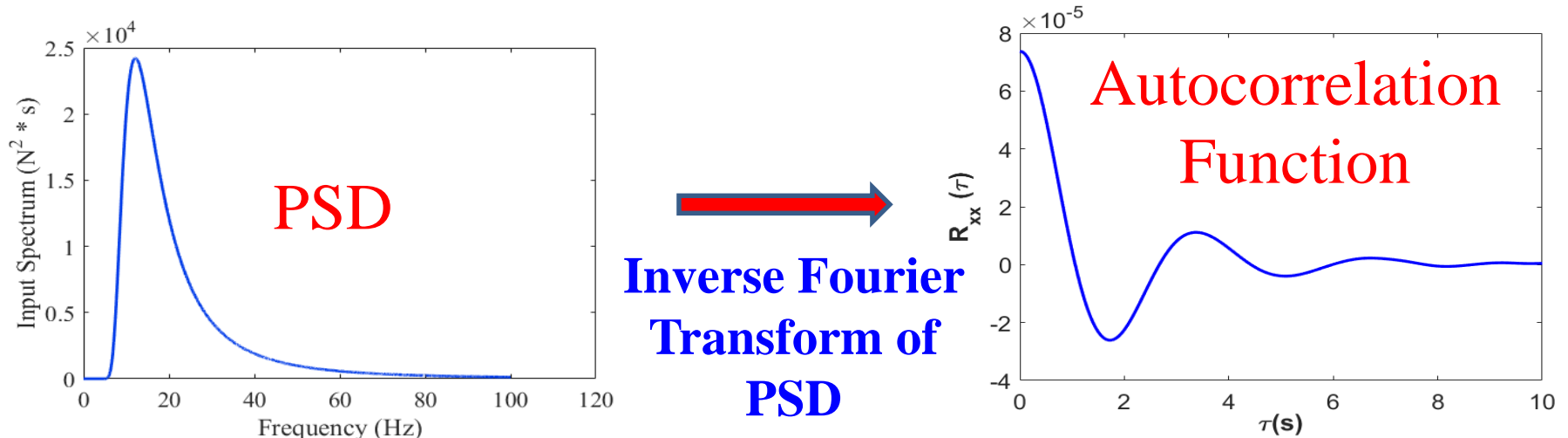
# Characterization of a Random Process



A zero mean, stationary Gaussian process is fully characterized by its autocorrelation function.

For a non-Gaussian process we need skewness and kurtosis in addition to the autocorrelation function.

# Simulation of a Gaussian Process in Time Domain



- Discretize the autocorrelation function and form the correlation matrix
- Obtain eigenvalues and eigenvectors of correlation matrix and use them in a Karhunen-Loeve (K-L) expansion

## K-L Expansion

$$\xi(t) = \sum_{i=1}^N \sqrt{\lambda_i} \cdot f_i(t) \cdot \xi_i$$

$\lambda_i$ : Eigenvalues of correlation matrix

$f_i(t)$ : Eigenvectors of correlation matrix

$\xi_i$ : Independent standard normal random variables

The number of required terms  $N$  increases fast with increasing simulation time

# Simulation of a Non-Gaussian Process (PCE-KL)

Express Non-Gaussian Process  $Z(t)$  in terms of Gaussian Process  $\xi(t)$  (PCE)

$$Z(t) = \sum_{i=0} b_i(t) \Psi_i(t) = b_0(t) + b_1(t) \xi(t) + b_2(t) (\xi^2(t) - 1) + b_3(t) (\xi^3(t) - 3\xi(t)) + b_4(t) (\xi^4(t) - 6\xi^2(t) + 3) + \Lambda$$

$b_i$ : coefficients to be calculated

$\xi(t)$ : Standard Normal Process

Use orthogonality of Hermite polynomials to calculate  $C_{\xi\xi}(t_1, t_2)$

$$C_{ZZ}(t_1, t_2) = \sum_{i=1} b_i(t_1) b_i(t_2) \cdot (i!) \cdot (E[\xi(t_1) \xi(t_2)])^i$$

$C_{ZZ}(t_1, t_2)$ : Covariance

Known (given)

Unknown (Calculate)  $C_{\xi\xi}(t_1, t_2) = E[\xi(t_1) \xi(t_2)]$

## K-L Expansion

$$\xi(t) = \sum_{i=1}^N \sqrt{\lambda_i} \cdot f_i(t) \cdot \xi_i$$

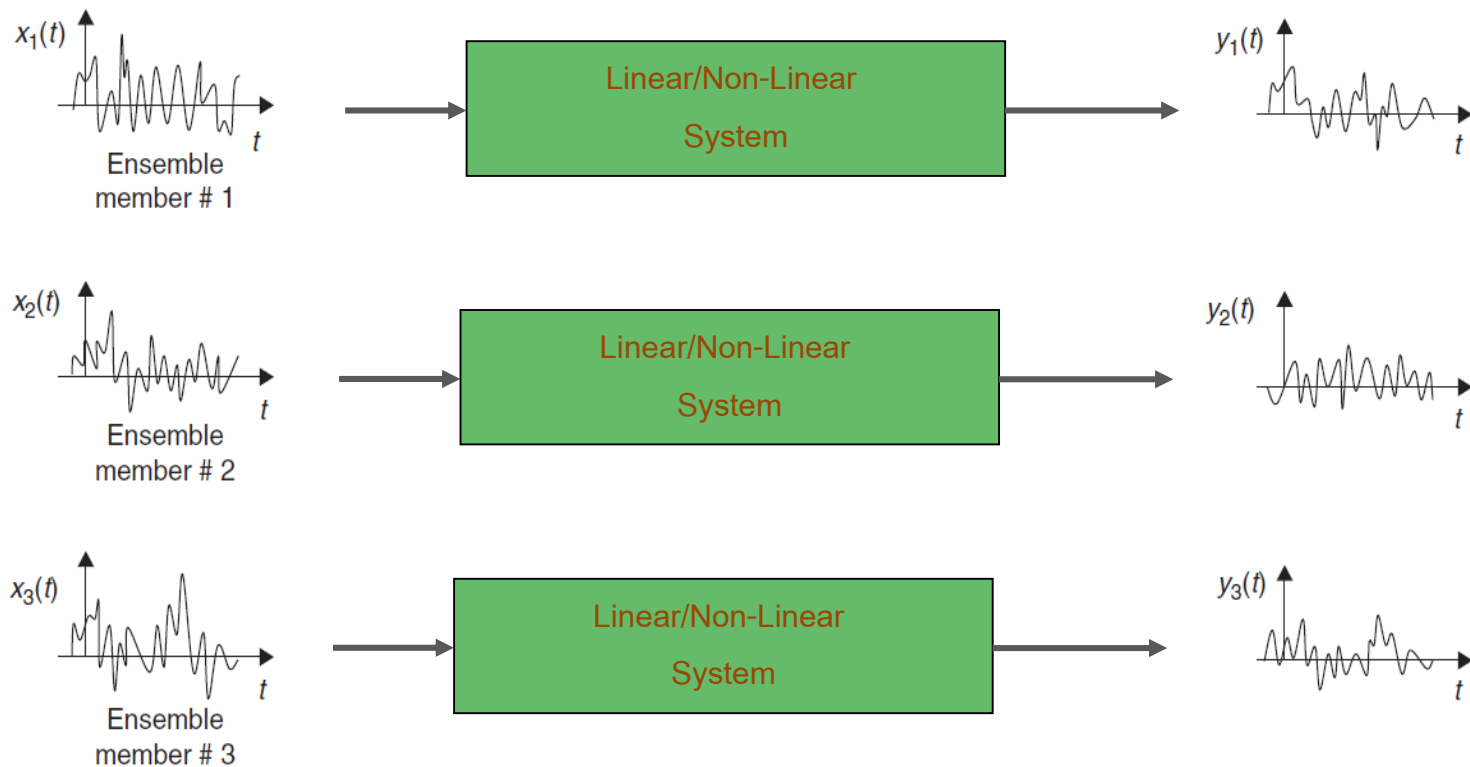
$\lambda_i$ : Eigenvalues of  $C_{\xi\xi}(t_1, t_2)$

$f_i(t)$ : Eigenvectors of  $C_{\xi\xi}(t_1, t_2)$

$\xi_i$ : Independent standard normal variables

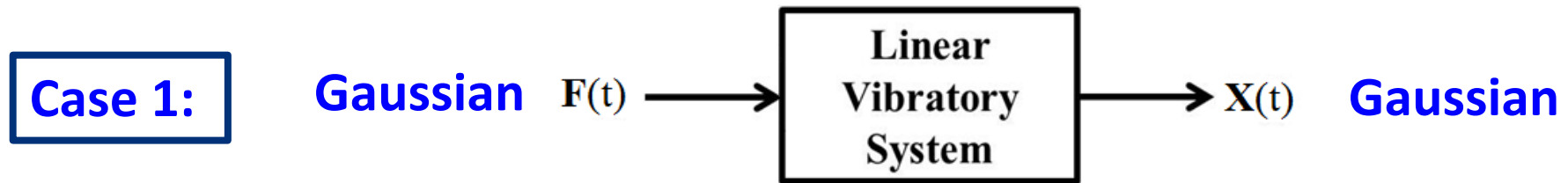


# Random Vibrations: Fundamental Tasks



- Sample functions (trajectories) must be generated for the **input** process (PCE – KL)
- Trajectories of **output** process must be calculated and used to quantify the output process (QMC). For efficiency, the simulation (calculation of output) time **must be short** (e.g. as long as the process correlation length)

# Characterization of the Output (Gaussian) Process for a Linear System



- A linear vibratory system is fully characterized by its **FRF** (Frequency Response Function)

$$S_{XX}(\omega) = |H(\omega)|^2 S_{FF}(\omega)$$

PSD of Output

FRF

PSD of Input

- **Linear Vibratory System**
- **Stationary & Gaussian Input**

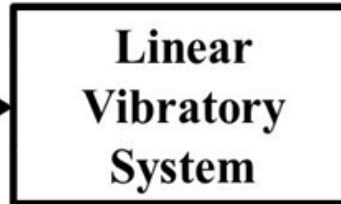
- An Inverse Fourier Transform of  $S_{XX}(\omega)$  yields the output autocorrelation function
- KL expansion using the output autocorrelation function yields trajectories of the output process

# Characterization of the Output (Non-Gaussian) Process for a Nonlinear System

**Case 2:**

Non-Gaussian

$F(t)$



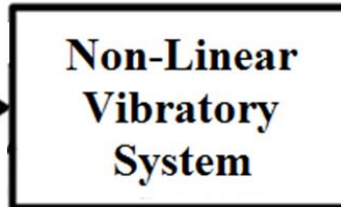
$X(t)$

Non-Gaussian

**Case 3:**

Gaussian

$F(t)$



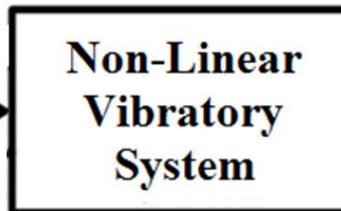
$X(t)$

Non-Gaussian

**Case 4:**

Non-Gaussian

$F(t)$



$X(t)$

Non-Gaussian

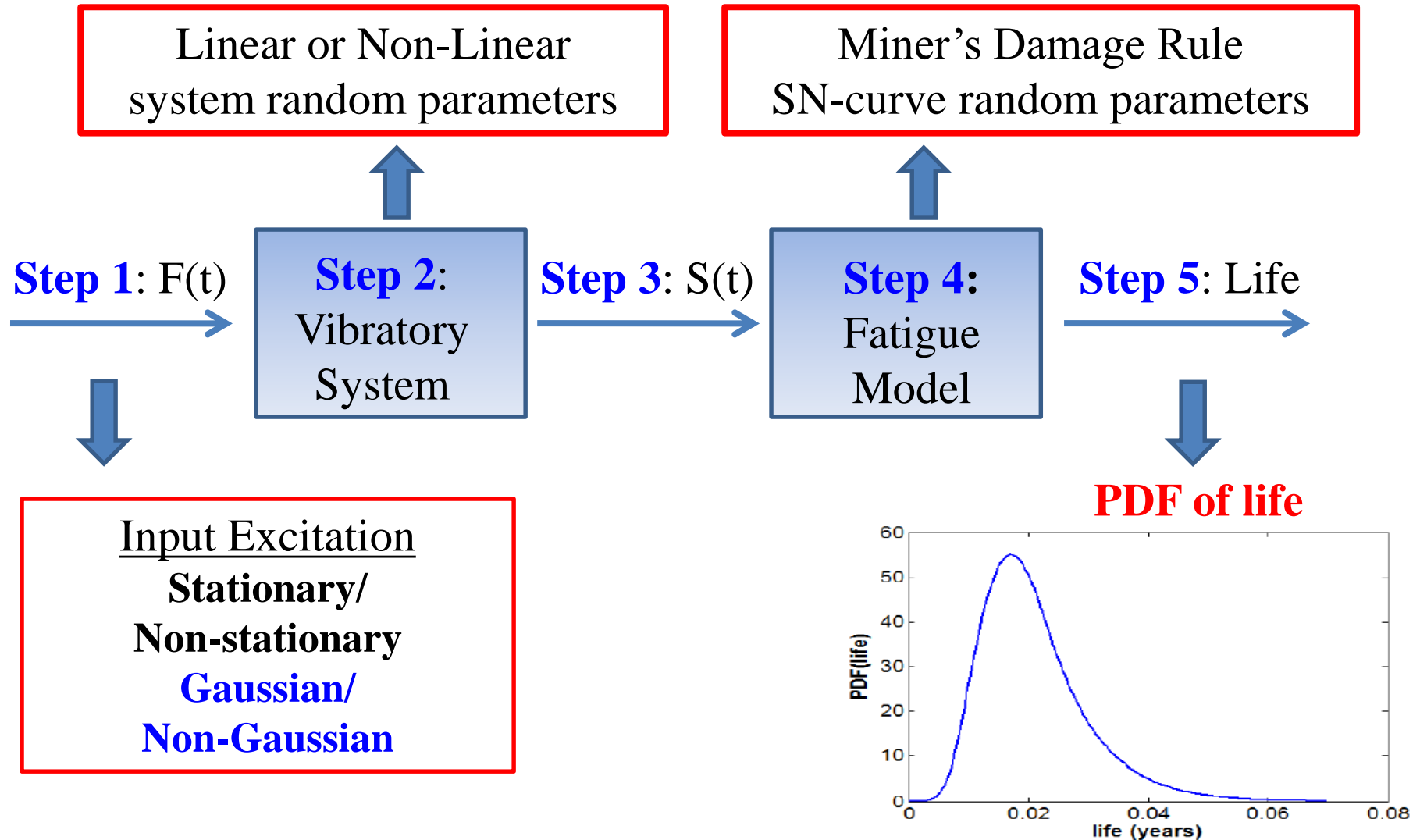
# Characterization of the Output (Non-Gaussian) Process for a Nonlinear System

- How can we use the calculated trajectories of the output process to characterize it accurately and efficiently?
- How many trajectories do we need? **The number of trajectories must be small for efficiency.**

## A Quasi Monte Carlo (QMC) approach is used

1. The  $N$ -dimensional  $(\xi_1, \xi_2, \dots, \xi_N)$  space is **space-filled** with  $M$  points
2. For each of the  $M$  points, a K-L trajectory  $\xi(t) = \sum_{i=1}^N \sqrt{\lambda_i} \cdot f_i(t) \cdot \xi_i$  of the input process is generated and the corresponding output trajectory is obtained
3. The above  $M$  output trajectories are used to estimate the 4 moments and autocorrelation function of the output process (QMC method)
4. Finally PCE-KL is used to characterize the output process

# Features of Methodology (Fatigue / Durability)

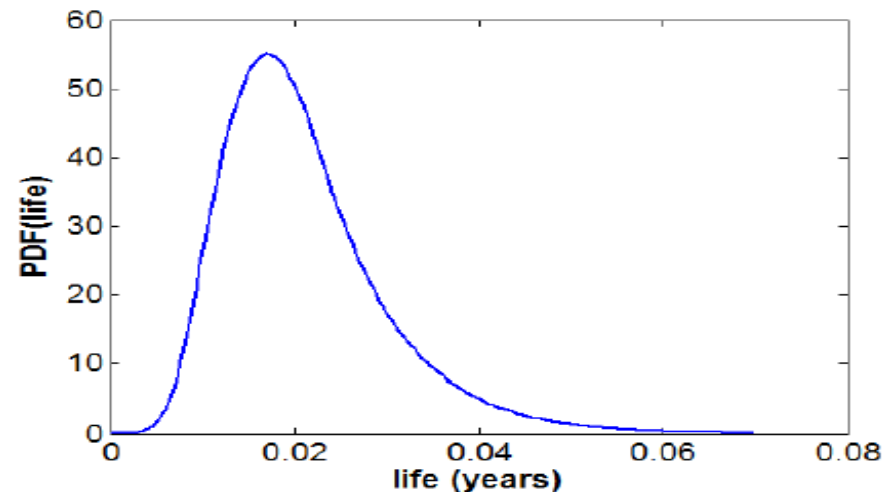


# Features of Methodology (Fatigue / Durability)

## Fatigue reliability:

- Characterize the **output** stress process (**PCE-KL-QMC**)
- Generate new output trajectories **without solving the system**
- **Rainflow counting method** to extract cycles
- **Miner's rule** to calculate the cumulative damage
- SPA to calculate the

**PDF of life**



# Features of Methodology (Fatigue / Durability)

## Design for fatigue:

The **system uncertainty** comes from:

- **System parameters** (e.g. stiffness of vehicle suspension)
- **Material properties** (e.g. S-N curve parameters)

Our **goal**:

- Modify mean values of system parameters to achieve a **fatigue life target** with high probability



**Reliability-Based Design Optimization (RBDO)**

# Features of Methodology (ALT)

## Accelerated Life Testing (ALT):

- Characterize Gaussian or non-Gaussian input excitation (e.g. PCE-KL)
- Reduce uncertainty of fatigue life prediction by performing tests at higher stress levels
- An optimization problem minimizes the cost of ALT testing while improving the accuracy of fatigue life prediction

Assumptions on Life Distributions and Stress-Life relationships are **lifted**



# Quarter Car Example: Fatigue Reliability

## Equations of Motion

$$m_1 \ddot{x}_1 + (c_1 + c_2) \dot{x}_1 - c_2 \dot{x}_2 + (k_1 + k_2) x_1 - k_2 x_2 = k_1 u + c_1 \dot{u}$$

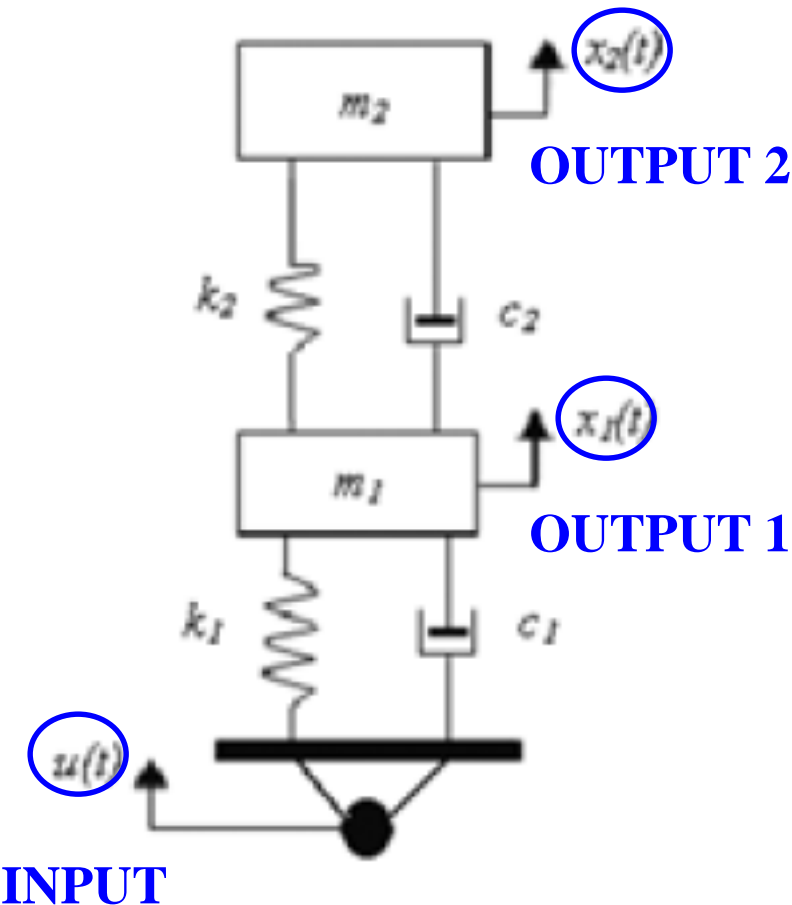
$$m_2 \ddot{x}_2 - c_2 (\dot{x}_1 - \dot{x}_2) - k_2 (x_1 - x_2) = 0$$

## Input Process $u(t)$

Non-Gaussian road elevation

## Output Stress Process $\tau(t)$

Function of spring deflection  
( $x_1 - x_2$ )



# Characterization of Input Process $u(t)$

## First 4 statistical moments

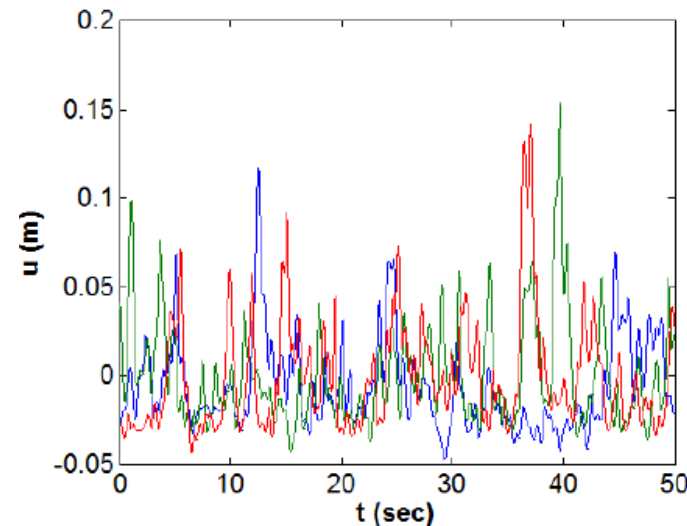
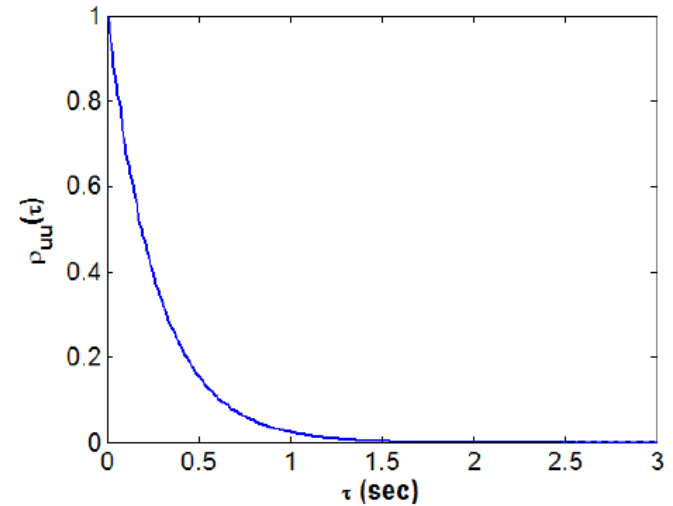
Quantity	Description	Value
$\mu_1$	Mean	0
$m_2 (= \sigma^2)$	Variance	0.001
$m_3 / \sigma^3$	Skewness Coefficient	2
$m_4 / \sigma^4$	Kurtosis Coefficient	10

**Note:** Same  $\mu_1$ ,  $m_2$ , PSD with a Gaussian road elevation according to **ISO 8608** standard



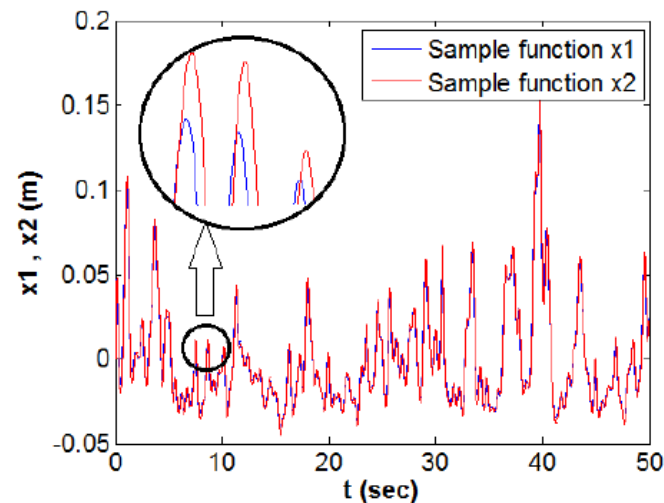
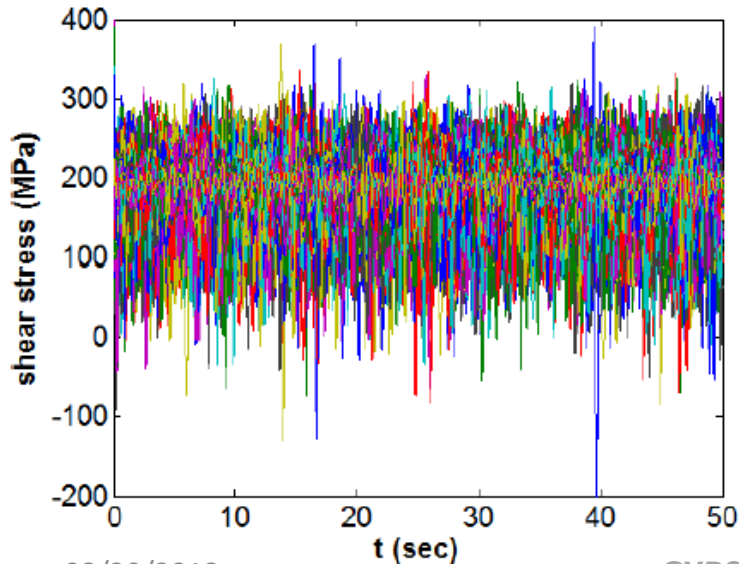
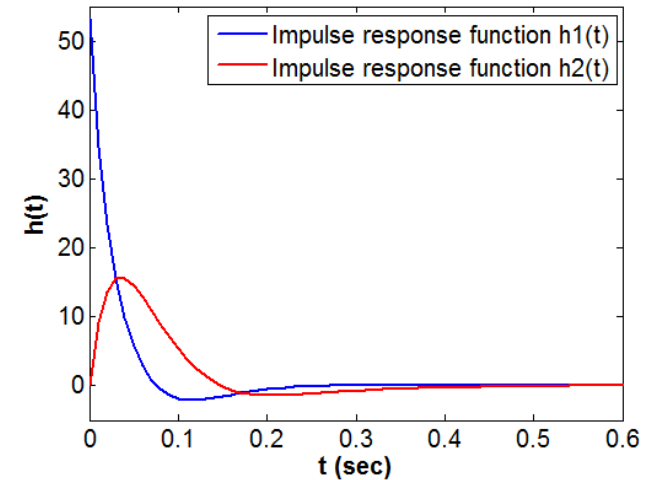
Create **PCE-KL** stochastic  
metamodel for **input** process  
and generate  
**trajectories of  $u(t)$**

## Autocorrelation



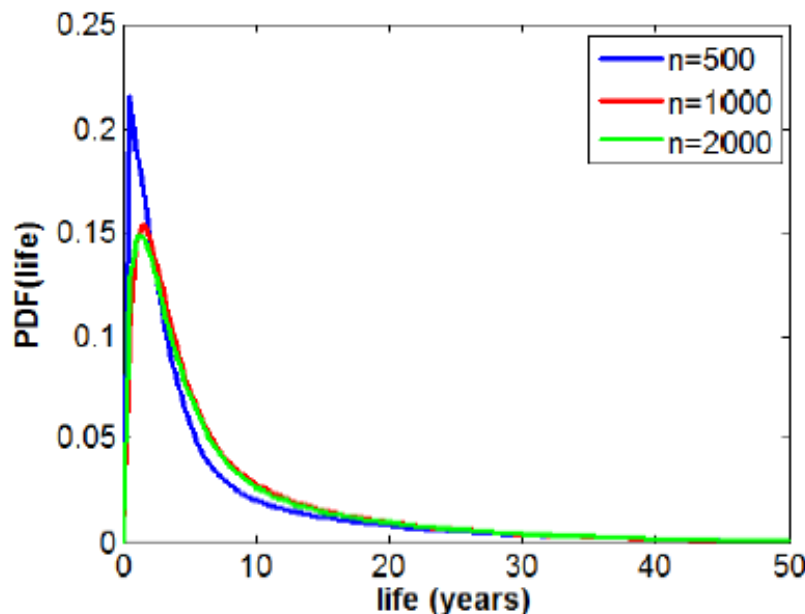
# Characterization of Output Stress Process $\tau(t)$

- Calculate the 4 moments & autocorrelation of output displacement processes  $x_1(t)$ ,  $x_2(t)$
- Develop PCE-KL stochastic metamodel for output stress process  $\tau(t)$
- Generate new trajectories of  $\tau(t)$  using the metamodel



# Estimation of PDF of Fatigue Life

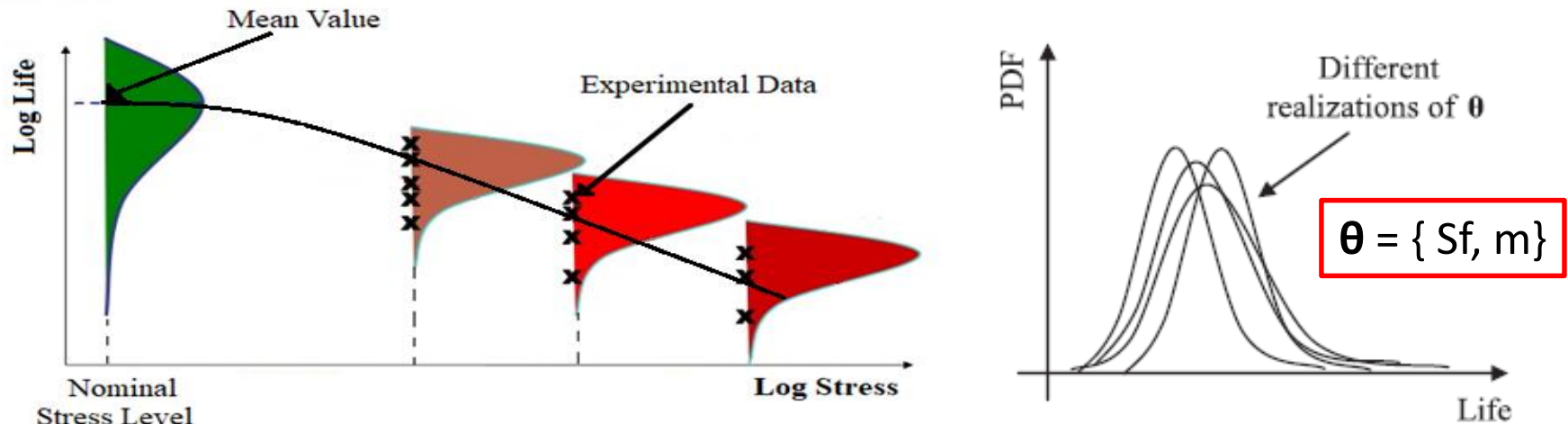
- Each output stress trajectory is rainflow counted and then Miner's rule is used to get a realization of cumulative damage  $D$
- SPA calculates the PDF of fatigue life ( $=1/D$ ) using the available realizations  $D_i$



Convergence is achieved for 1000 trajectories of output stress process

**Note:** This approach predicts the **entire PDF of fatigue damage** (not only the  $E(D)$ )

# Current Accelerated Life Testing (ALT) Process



**Uncertainty** in S-N curve parameters  $S_f$  and  $m$

## Steps of current ALT design process

1. Determine the stress levels
2. Assume a life distribution (Weibull, Lognormal, etc.)
3. Assume a stress-life relationship
4. Estimate distribution parameters (MLE) using test data
5. Calculate product reliability  $R_{s_0}$  at nominal conditions

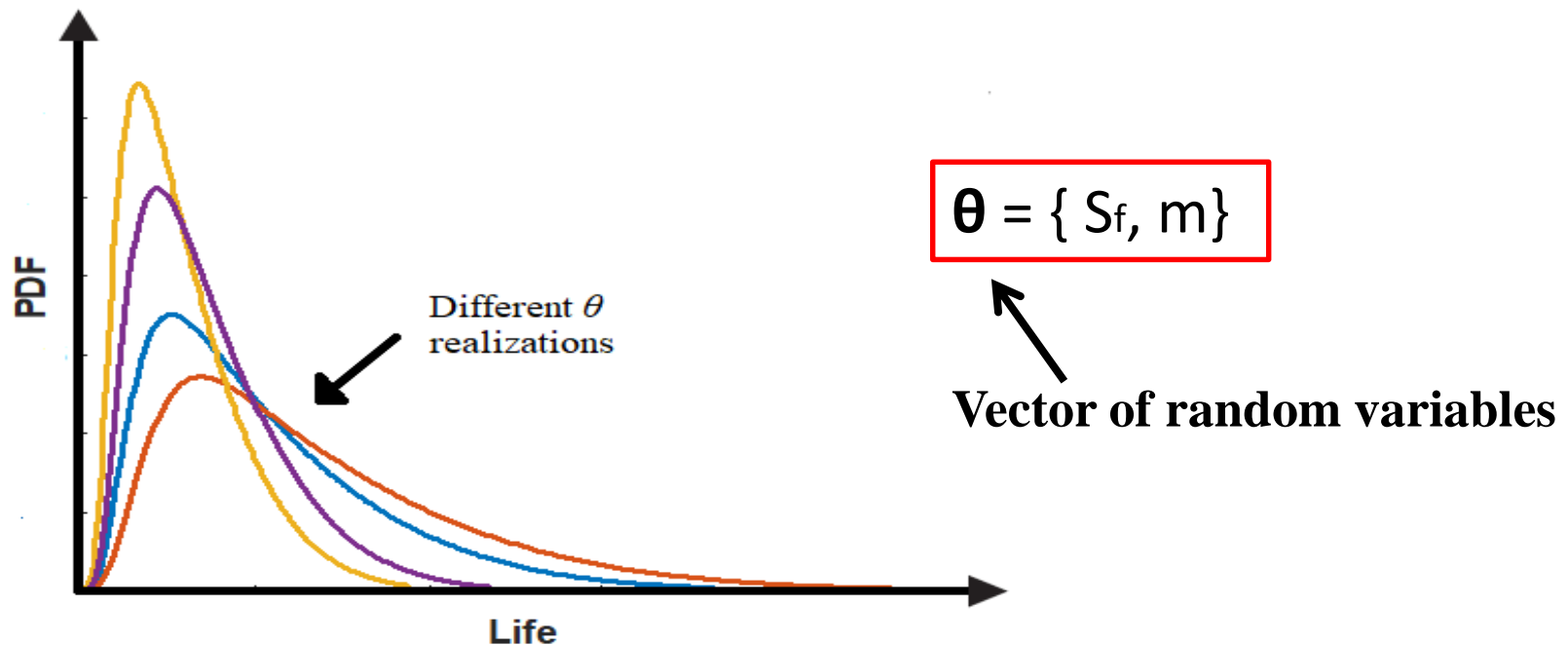
Parameters determined from experiments

$$\mu_T(S) = \alpha_1 + \alpha_2 \log(S)$$

# Enhanced ALT Design using SPA

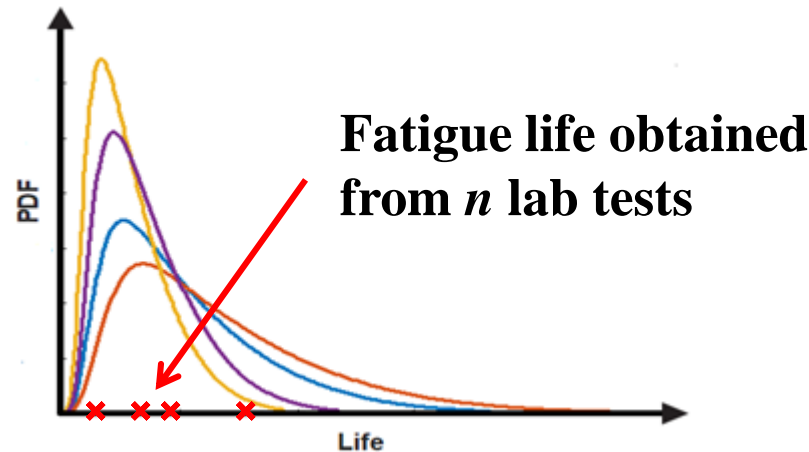
1) Calculate the **PDF** of fatigue life at elevated stress level using **SPA** for different realizations of uncertain parameters (i.e.  $S_f$  and  $m$  of S-N curve)

**No assumption** of **underlying life distribution** is made



# Enhanced ALT Design using SPA

2) Formulate a Likelihood Function to estimate the uncertain model & material parameters



$$L(\theta) = f(x_1; \theta) \cdot f(x_2; \theta) \cdot f(x_3; \theta) \cdots f(x_n; \theta)$$

$\theta$ : Vector of uncertain model & material parameters

$f_i(\cdot)$ : PDF of fatigue life using SPA (Saddlepoint Approximation)

$x_i$ : Life for  $i$ th experiment,  $i=1, 2, \dots, n$

# Enhanced ALT Design using SPA

3) Solve following **optimization problem** to obtain the **MLE values** of the **uncertain model & material parameters**

$$\max_{\theta, n} L(\theta) \longrightarrow \text{Calculated using SPA}$$

$$s.t \quad 1 \leq n \leq n_{\max} \longrightarrow \text{Number of lab experiments. The } n_{\max} \text{ depends on the available budget for lab tests}$$

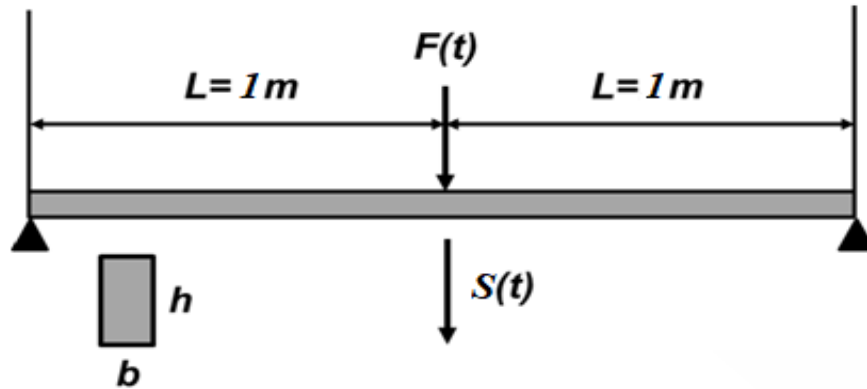
$$\theta_{\min} \leq \theta \leq \theta_{\max} \longrightarrow \text{Vector of uncertain model & material parameters}$$

4) Use **Fisher information theory** to obtain the **confidence interval** of  $\theta$

5) Calculate **reliability** of the system at **nominal conditions**



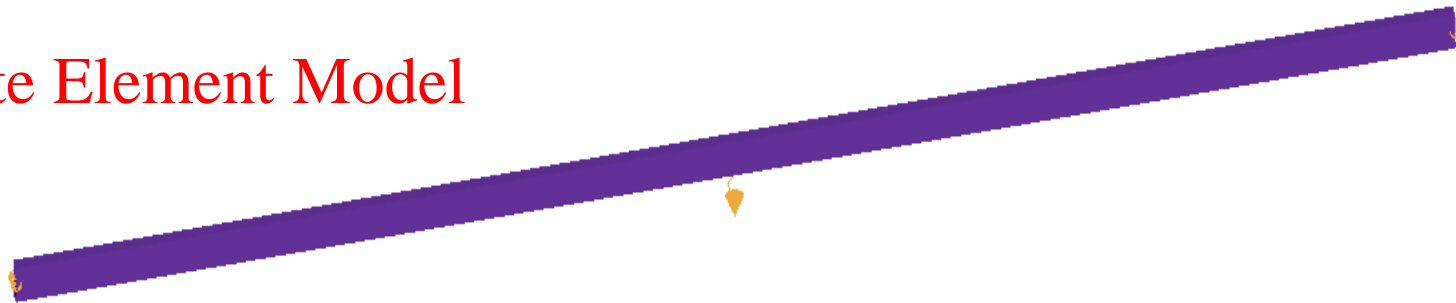
# ALT Example: Simply Supported Beam



**$F(t)$ :**  
Input Load process (Gaussian)

**$S(t)$ :**  
Output Stress process

Finite Element Model



Uncertain Model & Material Parameters

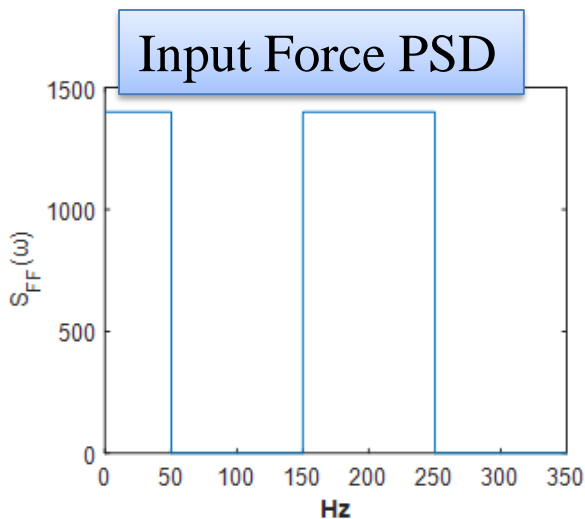
$$\theta = \{S_f, m\}$$

(parameters of S-N curve)

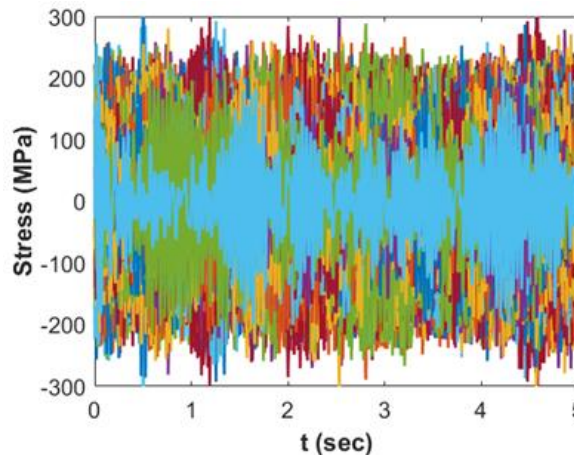
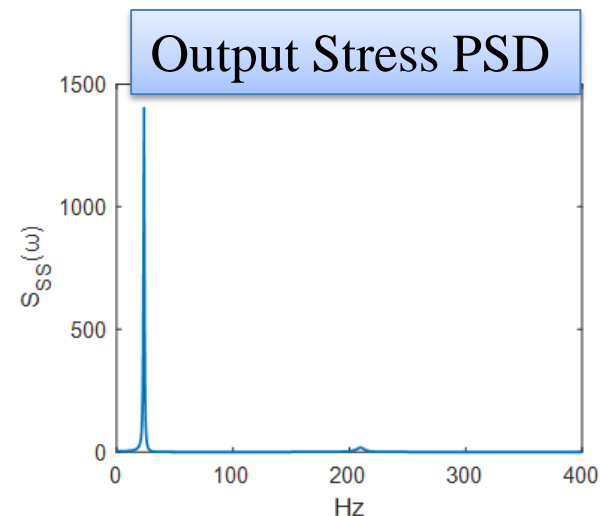
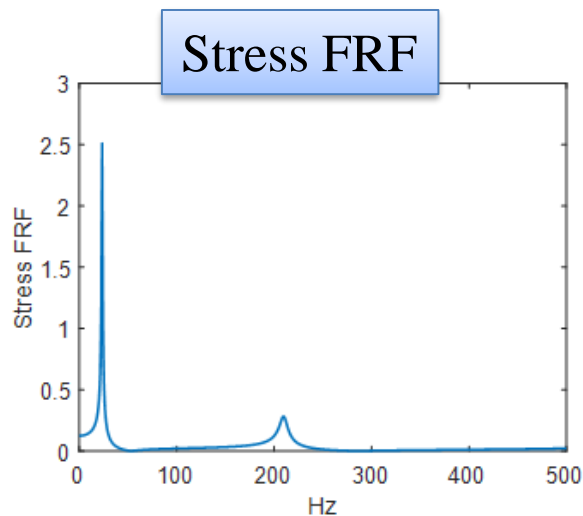
Variable	Mean	Standard Deviation	Distribution
$S_f$	1298	129.8	Gaussian
$m$	5.56	0.556	Gaussian

# ALT Example: Simply Supported Beam

## Linear System



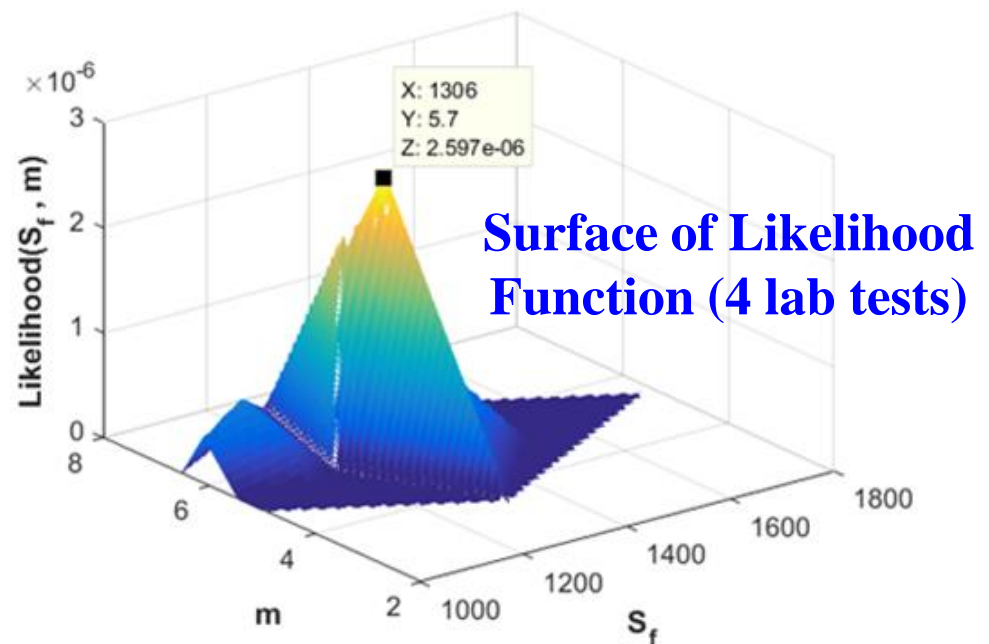
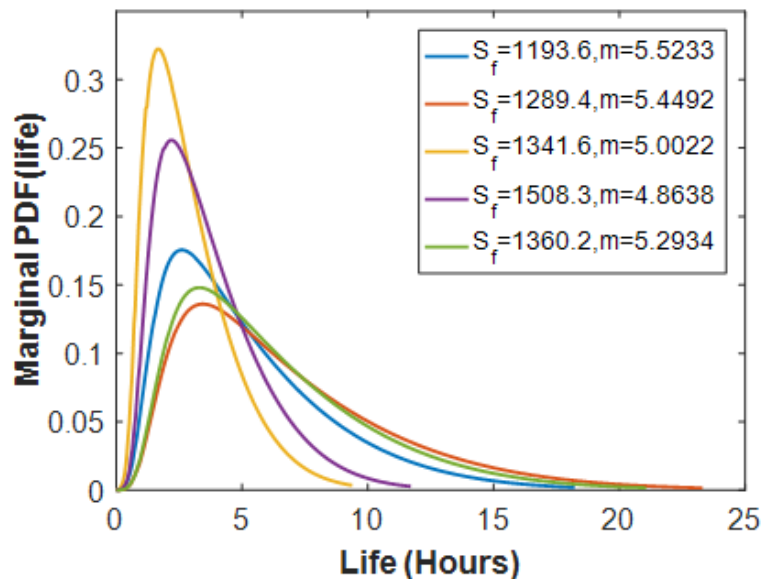
↙  
Inflated, without  
violating the failure  
modes of the system



↘ Generate stress  
trajectories  
(Karhunen-Loeve  
expansion)

# ALT Example: Simply Supported Beam

- For a random sample of  $(S_f, m)$ , each stress trajectory is **rainflow counted** and **Miner's rule** is applied to estimate fatigue life.
- **Saddlepoint approximation** estimates the **PDF** of fatigue life for the  $(S_f, m)$  sample. The respective **likelihood value** is calculated for a given number of tests.
- Optimization determines the optimum value of  $(S_f, m)$  and number of tests  $n$ .



# ALT Design Optimization Results

- Fisher Information theory provides the **confidence interval** of estimated model and material properties

Confidence Intervals

# Experiments	$\bar{S}_f$	$\hat{m}$
1	1400.42	5.4344
2	1400.36	5.3481
3	1399.61	5.4340
...	...	...
9	1306.56	5.6348
10	1306.56	5.6700
11	1306.56	5.6700
12	1306.56	5.6700
20	1306.56	5.6700
50	1306.56	5.6700



10 experiments are enough to obtain the calibrated MLE values of uncertain parameters

# Experiments	$S_f$		m	
	90% Confidence Interval			
	Lower	Upper	Lower	Upper
1	0	2846.1	2.69	8.65
2	688.4	1923.6	4.45	6.89
3	528.0	2084.0	4.17	7.17
...	...	...	...	...
9	555.7	2056.3	4.24	7.10
10	673.4	1938.6	4.46	6.88
20	1126.8	1485.2	5.32	6.02
30	1149.9	1462.1	5.37	5.97
40	1180.9	1431.1	5.42	5.92
50	1268.1	1343.9	5.61	5.73

# Summary & Conclusions

- A novel random vibrations approach for **vibratory systems** excited by **non-Gaussian** processes was presented using PCE, KL and QMC.
  - Applications in reliability and durability
- An **ALT methodology** to estimate fatigue life was presented.
  - **No assumption** for the **life distribution** and **stress-life relationship**
  - The **uncertainty** in **model** and **material properties** is **considered**
- Examples demonstrated the presented approaches

**Thank you for your attention**

`mourelat@oakland.edu`

**Q & A**